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A CALCULATION PROCEDURE FOR VISCOUS FLOW
IN TURBOMACHINES - VOL. III

BY

I. KHALIL, Y. SHEORAN AND W. TABAKOFF

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FORTRAN PROGRAM FOR CALCULATING VISCOUS FLOW
ON A BLADE-TO-BLADE STREAM SURFACE OF A TURBOMACHINE

SUMMARY

A method for analyzing the nonadiabatic viscous flow through turbomachine blade passages is presented. The field analysis is based upon the numerical integration of the full incompressible Navier-Stokes equations, together with the energy equation on the blade-to-blade surface. A Fortran IV computer program has been written based on this method. The numerical code used to solve the governing equations employs a nonorthogonal boundary fitted coordinate system. The flow may be axial, radial or mixed and there may be a change in stream channel thickness in the through-flow direction.

The program input consists of the configuration of the stream channel annulus S_1 , the blade-to-blade stream channel weight flow, the inlet flow conditions, and outlet flow angle, and the rotational speed of the machine. The output includes the distribution of the stream function, the vorticity, the static pressures within the blade passages, and the variation of meridional and tangential velocity components from blade-to-blade and from the inlet of the machine to its exit are moreover generated. The program also has the capability to generate the temperature distribution within the blade passages in case the blade cooling is under consideration.

This report includes a complete description of the inputs required for two Fortran IV programs. The first program considers laminar flows and the second can handle turbulent flows. Numerical examples have been included to illustrate the use of the program, and to show the results that are obtained.

INTRODUCTION

An attempt is made to demonstrate the feasibility of obtaining viscous flow details within turbomachine passages by appropriately combining several blade-to-blade viscous flow solutions. Each of these solutions is obtained through the numerical integration of the full incompressible Navier-Stokes equations over a predetermined stream surface that extends between the blades. The set of stream surfaces required for the analysis are themselves generated from the solution of the nonviscous version of the Navier-Stokes equations.

This report is presented in two parts. Part I includes a description of the input to the laminar viscous flow Fortran IV program and the interpretation of its output. A numerical example has been included to demonstrate the use of the program. The example includes flow in a radial inflow turbine.

Part II presents the procedures for computing turbulent viscous flow details within turbomachine passages. This part discusses the input and output, with a numerical example to demonstrate its use as a turbulent viscous flow analyzer.

The present report forms the final volume of a three volume report. This volume is organized as a user's manual to serve an individual desiring to use the program. For those who wish to study the calculation procedures and the mathematical analysis in detail and need to modify the program to suit their needs, this report will have to be used in conjunction with the theoretical procedure which forms the contents of Vol. I and Vol. II [2, 7]. The entire report is organized such that a design engineer desiring the use the program need only read the sections NUMERICAL EXAMPLE and DESCRIPTION OF INPUT AND OUTPUT, of Part I alone or both Part I and Part II. If only laminar viscous flow details are needed then reading Part I would suffice. However, if turbulent viscous flow details are sought then both Part I and Part II should be read. Both sections have been organized into decimal numbered subsections, and accordingly a decimal numbered system is used for the equations and figures. This numbering system is adopted for the ease of handling the two parts

with overlapping information and frequent cross references. In this decimal numbering system, the first number refers to the part of the report in which the section, equation or figure exists and the subsequent numbers refer to subsection.

PART I

1.1 NUMERICAL EXAMPLES

To illustrate the use of the program and to show the type of results which can be obtained, a numerical example is given.

Radial Inflow Turbine

An example turbine rotor profile is shown in Fig. 1.1. First a meridional plane analysis was made by the quasi-orthogonal method of reference [1] to establish the stream channel geometry and the stream annulus thickness distribution. The flow patterns are investigated on this blade-to-blade stream channel, S_1 , located midway in the passage depth of the rotor as shown in Fig. 1.1. The results presented here are case 2 of reference [2]. The primary reason for the selection of this specific rotor is that a substantial amount of experimental data is available for comparison [3]. The input data for the program are given in Table 1.I. A sample of the output of the program is presented in Tabale 1.II. The streamlines are designated by the stream function ratio ψ/ψ_{total} . Such streamline contours are plotted in Fig. 1.2 along with the streamlines determined experimentally. Also presented here are the velocity profile at three radial locations as shown in Fig. 1.3. For the purpose of comparison the inviscid flow profiles, indicated by dotted lines, are superimposed on the viscous profiles in Fig. 1.3. For a more detailed discussion of these results, Vol. I of this report should be referred [2].

Radial Compressor Rotor

This example is a rotor of a radial bladed compressor of reference [4]. The rotor profile is shown in Fig. 1.4. First,

a mid-channel stream surface, S_1 , and the stream annulus thickness are calculated by the meridional flow analysis of reference [1]. A typical distribution of the flow properties on the blade-to-blade stream annulus, S_1 , of Fig. 1.4 are calculated and the corresponding results are presented.

The results of radial compressor rotor flow are presented solely for the sake of demonstrating the capability of the program. Therefore only the final results are discussed. The preparation of input and interpretation of output is similar to the previous turbine example. A comparison between the predicted streamline contours and those determined experimentally in reference [4] are plotted in Fig. 1.5. The experimental evidence was obtained by tracing photographs of streak lines from the rotor segments under the same operating conditions reported here. A good agreement is generally observed. The predicted meridional velocity profiles across the rotor passage at three different radial locations are illustrated in Fig. 1.6. Shown also in the same figure, are the calculated velocity distribution using the inviscid blade-to-blade analysis of reference [5].

1.2 DESCRIPTION OF INPUT AND OUTPUT FOR LAMINAR VISCOUS FLOW PROGRAM

The computer program requires as input appropriate gas constants, operating conditions such as inlet temperature and density, inlet and outlet flow angles, weight flow, rotational speed, and information regarding the overlaying of grid in the flow passage. Figure 1.7 shows the $m-\theta$ coordinate system for a typical blade-to-blade surface which includes the physical flow domain. Also required as input is the stream surface geometry and transformation parameters at every grid point. The latter part of the input is obtained as a consequence of applying Thompson transformation to the blade. Output obtained from the program includes velocity magnitude and direction at all mesh points (meridional and tangential velocity), value of nondimensional vorticity, Reynolds number and pressure coefficients at each mesh point.

Input

Figure 1.8 shows the input form indicating the variables as they are punched on the data cards. There are two types of variables, geometric and nongeometric. The geometric input variables are shown in Figs. 1.9 and 1.10. A description of all the input variables is listed in this section.

Further explanation of key variables is given in the section, Instructions for Preparing Input. The input variables, in order of their appearance, are as follows:

AMU	Kinematic viscosity ($N \cdot s/m^2$)
PRDNO	Prandtl number
TIP	Total inlet temperature of the turbine ($^{\circ}K$)
TBLADE	Blade temperature ($^{\circ}K$)
RHOIP	Total inlet density (Kg/m^3)
WTFL	Mass flow rate per blade, per stream channel, (Kg/sec)
OMEGA	Rotational speed of the machine (revolutions/sec)
BTI	Inlet flow angle to the machine (deg), (see Fig. 1.9)
BTO	Outlet flow angle to the machine (deg), (see Fig. 1.9)
BLADE	Number of blades
BIN	Inlet stream channel thickness, (m)
RTIP	Tip radius of the rotor, (m)
RIN	Inlet radius of the machine at upstream boundary AN, (m)
MXBI	Number of vertical mesh lines from AN to BM inclusive, (fig. 1.10)
MXBO	Number of vertical mesh lines from AN to FI inclusive, (Fig. 1.10).
MX	Total number of vertical mesh lines in m-direction from AN to GH; maximum of 50, (Fig. 1.10)
NBBI	Number of mesh spaces on ϕ direction between AB and NM; maximum of 30 (Fig. 1.10)
ITRB	-1 for turbine case; +1 for compressor
IPRINT	The number of iterations after which the output should be printed.

ISPL	For a straight blade, ISPL is assigned any integer value other than zero, otherwise it is left blank or zero. If ISPL is zero, then appropriate number of transformation parameters follow the stream surface configuration
AMM(I)	Array of m coordinate corresponding to mesh points (m)
R(I)	Array of r coordinate corresponding to AMM(I) array, (m)
SAL(I)	Array of $\sin\alpha$, (see Fig. 1.10)
BRO(I)	Array of stream channel normal thickness corresponding to the AMM(I) array, (m)
UTR(I,N)	Transformation parameter ($\equiv \frac{\partial X}{\partial \eta}$) [Note: $\partial X = \frac{\partial m}{r}$]
VTR(I,N)	Transformation parameter ($\equiv \frac{\partial Y}{\partial \eta}$) [Note: $dY = d\phi$]
VIC(I,N)	Transformation parameter ($\equiv \frac{\partial X}{\partial \xi}$)
UIC(I,N)	Transformation parameter ($\equiv \frac{\partial Y}{\partial \xi}$)
THETA(I,N)	Array of ϕ coordinate at each mesh point.

Instructions for Preparing Input

Units of Measurements:

The International System of Units is used throughout this report. The program does not use any constants which depend on the system of units being used. Therefore any consistent set of units may be used in preparing the input for the program. However, the angles must be supplied in degrees unless indicated otherwise, and the rotational speed is given in revolutions per second. Since any consistent set of units can be used, the output is not labeled with any units. In the examples supplied, the International System of Units are used.

Stream Surface Geometry:

The stream surface on which the flow is being determined, is a surface of revolution. Hence it is sufficient to define the mean stream surface of revolution (as seen in meridional plane, Fig. 1.9a). The stream surface required for the analysis is generated from the solution of a nonviscous version of the Navier-

Stokes equation as suggested by Wu [6]. The mean stream surface is defined by a set of m -coordinates and corresponding arrays of radii, sine of the angle made by the m -coordinate to the machine axis and the stream thickness for each ' m '.

Inlet and Outlet Flow Angles:

The value of β_{inlet} is given as an average value on AN. The exit flow angle β_{exit} is found iteratively. Normally one or two trial runs of the program are required to arrive at the exit flow angle. The iterative procedure is as follows. Estimated exit flow angle, β_{exit} , along GH is used to specify the values of stream function derivatives in the m -direction through the following relation

$$\frac{\partial \psi}{\partial m} = \frac{1}{2\pi/z} \frac{\tan \beta_{exit}}{\gamma_{exit}} \quad (1.1)$$

The flow field equations are then solved for the boundary function ψ given by equation (1.1) to obtain the velocity and pressure distribution throughout the stream annulus S_1 of Fig. 1.7. An evaluation of the torque developed by the annulus is obtained through the integration of the pressure and shear forces acting on the blade surfaces. The change in the annulus momentum between the known inlet and the estimated exit flow conditions is determined. If now the value of the predicted torque is not equal to the rate of change of the angular momentum, then the direction of the exit flow velocity is altered. The whole procedure is repeated until a satisfactory result is obtained.

Defining the Mesh:

A finite-difference mesh is used for the solution of the basic differential equation. A typical mesh pattern is shown in Fig. 1.11. The mesh spacing and the extent of the upstream and downstream regions are determined by the values of MXBI, MXBO and MX of the input. The program is presently set up to accept a maximum of 30 for MX. This is not a necessary constraint, the limit can be changed with very little effort. The values of MXBI, MXBO and MX should be determined such that the mesh

which results has blocks which are approximately square. To achieve this, a value for NBBI is first chosen arbitrarily (15 to 20 typical). NBBI is a number of mesh spaces spanning the blade pitch S , where $S = 2\pi/\text{BLADE}$. Dividing S by NBBI gives the mesh spacing DN in the θ -direction in radians. Multiplying DN by an average radius (RIN) of the stream channel gives an average value of the actual mesh spacing in θ -direction. The value of axial chord of the blade should then be used with this tangential mesh spacing to calculate the approximate number of mesh spaces along the blade in the m -direction. This will give MXBO once MXBI is chosen.

Format for Input Data:

All the numbers on the first and second cards (Fig. 1.8) beginning with AMU and BTI respectively are real numbers (punch decimal point) in a 10-column field. The numbers on the third card beginning with MXBI are integers (no decimal point) in a five-column field (Fig. 1.8). And finally, all other numbers following the fourth card are real numbers specified in E format in a 14-column field.

Output

A sample output is shown in Table 1.1 for the radial inflow turbine rotor example. Since the complete output would be lengthy, only the first few lines of each section of output are reproduced here. Each section of the sample output in Table 1.1 has been numbered to correspond to the following description:

(1) The first output is an echo of the input data from Fig. 1.8. This comprises of sections (1a) and (1c). Though (1b) is not strictly an echo of the input data, it is useful for the future correction of the input data as explained in the section, Defining the Mesh. This is a printout of DS and DN, the grid spacing in the m -direction and θ -direction, respectively.

(2) This is the output which consists of blade transformation parameters. The output is displayed for each mesh point and begins from the line of constant $\eta = 1$ till the last η .

(3) These are the mean relative velocity at the inlet (WMIN) and the inlet Reynolds number.

(4) This is the maximum iteration required, the maximum values of the stream function, and the maximum value of the vorticity in the flow field.

(5) The values of the stream function, the meridional velocity, the tangential velocity, the vorticity and the pressure coefficient are displayed for each mesh point. These quantities are presented in groups along constant η lines.

1.3. PROGRAM PROCEDURE

The program is segmented into seven main parts, the subroutines VORT, STREAM, STAPRD, STORE, TEMP, CONVERG and subroutine function SPLINE are called by the main program. All the subroutines and their relations are shown in figure below. All information which must be transmitted between the seven main subroutines is placed in COMMON.

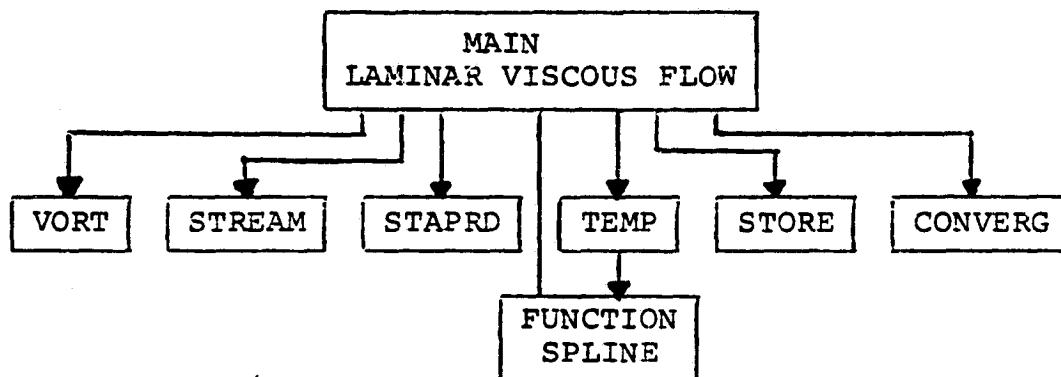


Fig. 1.12. Calling Relations of Subroutines.

The program was run on AMDAHL 470/V6-11 central processing unit with six magabytes real data storage. The program is presently set up to handle 30 by 40 mesh points; this was chosen to keep the running time reasonable. If, however, the user needs to use more mesh points, or if there is a storage problem on the user's computer, the maximum number of mesh points can be increased or reduced as the case may be by appropriately altering the dimension and common statements.

TABLE 1.1. INPUT DATA CARD LISTING.

RUN NO.	AMM	INPUT DATA CARD LISTING		TILADF TIP	W1EL	WNEGA
		PRODN	1000.000			
1a	-0.007079	0.000000	500.000	-1.000000	-30000000-02	-4030.000
	-0.007079	0.000000	500.000	-1.000000	-30000000-02	-4030.000
	0.003684	9.0	0.083527	-1.004280	0.000967	0.000967
	0.0	0.080123	0.080123	-1.000120	0.000956	0.000956
	0.003498	0.0	0.076450	-0.993984	0.000960	0.000960
	0.006653	0.0	0.072986	-0.985732	0.000982	0.000982
	0.010048	0.0	0.069697	-0.974760	0.001013	0.001013
	0.013104	0.0	0.066603	-0.960602	0.001043	0.001043
	0.016034	0.0	0.063701	-0.937357	0.001068	0.001068
	0.018845	0.0	0.060999	-0.904973	0.001090	0.001090
1b	0.021535	0.0	0.058511	-0.862245	0.001110	0.001110
	0.024127	0.0	0.056253	-0.810406	0.001128	0.001128
	0.026630	0.0	0.054236	-0.749061	0.001144	0.001144
	0.029055	0.0	0.052443	-0.681938	0.001156	0.001156
	0.031413	0.0	0.050874	-0.610477	0.001160	0.001160
	0.033711	0.0	0.049519	-0.540900	0.001155	0.001155
	0.035599	0.0	0.048348	-0.478504	0.001157	0.001157
	0.046662	0.0	0.047338	-0.420336	0.001179	0.001179
	0.048730	0.0	0.046477	-0.360370	0.001216	0.001216
	0.050782	0.0	0.045762	-0.299578	0.001253	0.001253
1c	0.042466	0.0	0.045177	-0.250202	0.001284	0.001284
	0.044574	0.0	0.044690	-0.21778	0.001416	0.001416
	0.052817	0.0	0.043155	-0.179872	0.001310	0.001310
	0.054835	0.0	0.042782	-0.190020	0.001441	0.001441
	0.056835	0.0	0.042466	-0.160095	0.001465	0.001465
	0.058816	0.0	0.043881	-0.180691	0.001362	0.001362
	0.060776	0.0	0.043516	-0.176406	0.001389	0.001389
	0.062217	0.0	0.041987	-0.200873	0.001420	0.001420
	0.062717	0.0	0.041570	-0.215980	0.001514	0.001514
	0.064639	0.0	0.041145	-0.220585	0.001540	0.001540

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TABLE 1.1 (Continued)

MULTI-FACTOR TRANSFER LEARNING PARADIGMS

PART II

2.1. NUMERICAL EXAMPLE

The equations formulated in Volume II [7] are programmed for numerical solution using the finite difference technique. The program is arranged to handle general flow within turbomachinery, which may be of the axial, radial or mixed flow type. To illustrate the use of the method of analysis a sample problem will be discussed. The input and output of the program will be presented.

Nonadiabatic Flow in a Mixed Flow Turbine

The versatility of the present method of solution is predicting the behavior of the viscous nonadiabatic flow in turbomachinery is demonstrated by analyzing the flow in a cooled mixed-flow turbine rotor. The rotor geometry is shown in Fig. 2.1 together with the shape and thickness distribution of the mid-channel stream annulus, S_1 . The blade-to-blade shape in the physical domain as well as the boundary fitted coordinates employed in the solution are shown in Figs. 2.2 and 2.3. Additional summary data related to the blades geometry and the configuration of stream annulus S_1 can be found in Table 2.1. The following operating conditions which correspond to the design point of the turbine are used in the analysis. The program output is presented in Tables 2.2 and 2.3.

Turbine inlet total temperature, T_t , 1083°K

Turbine inlet density, ρ , 1.0060 Kg/m^3

Mass flow per blade for the stream annulus, \dot{m} , 0.00320 Kg/sec

Rotational speed, Ω , 38,500 rpm

Inlet flow angle, β_{in} (see Fig. 1.10), 62.5°

Exit flow angle, β_{exit} (see Fig. 1.10), 63°

Meridional component of the relative velocity at rotor inlet, w_m , 66.2 m/s

Flow Reynolds number at rotor inlet, Re ($\equiv \frac{\rho w_m r_{tip}}{\mu_e}$), 3.34×10^5

Prandtl number, 0.8

Working fluid, air.

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The results are presented in Figs. 2.4 through 2.9 as contour plots for the distribution of the stream function, the velocity, the kinetic energy of turbulence, the static pressure as well as the temperature within the blade passages. The detailed discussion of these results will be found in reference [7].

2.2. DESCRIPTION OF INPUT AND OUTPUT FOR TURBULENT VISCOS FLOW PROBLEM

The program requires as an input the configuration of the stream channel annulus S_1 , the inlet flow conditions, the rotational speed of the machine, and the blade geometry. Recalling that all the flow calculations are carried out in the unit square of the transformed domain, therefore the blade input geometry is supplied to the program in the form of the transformation parameters δ , β , γ and J . As pointed out in reference [1], these parameters may be specified for any blade geometry using Thompson code for the automatic numerical generation of boundary fitted coordinate system [13].

The program output consists of the distribution of the stream function, the vorticity, the kinetic energy of turbulence, its dissipation rate, and the static pressures within the blade passages. The variation of meridional and tangential velocity components from blade-to-blade and from the inlet of the machine to its exit are also generated. In cases where blade cooling is considered, the program has the capability to generate the temperature distribution within the blade passages. In order to keep the computer time within reasonable limits, (usually less than 5 minutes on an ANDAHL 470), the flow domain has been divided, for all calculations, into 30 step sizes in η direction and 40 in the ζ direction, with the greater number of nodes distributed in the meridional direction.

Input

The description of the input variable, the input form (Fig. 1.8) and their formats are presented in Part I of this report and are valid for the turbulent program. Also the comments made about Units of Measurements, Stream Surface Geometry, Inlet and Outlet Flow Angles, and Defining the Mesh, in the section, "Instructions for Preparing Input," of Part I hold good for the turbulent program presented here in Part II.

Output

However, the output for the turbulent program needs some more explaining. The sample output is shown in Table 2.2 and Table 2.3. Here again, since the complete output would be lengthy only parts of all relevant output are reproduced in the two Tables 2.2 and 2.3. Each section of the sample output in Table 2.2 and Table 2.3 are sequentially numbered in subdivisions to correspond to the following description:

(1) The first output is an echo of the input data. This comprises of sections (1a) and (1c). The output in section (1a) is identically described in Fig. 1.8. Section (1c) displays the blade geometry data. Though section (1b) is not an echo of the data, it is an important derived quantity DS and DN, the mesh spacings. These are displayed to help adjust the mesh size.

(2) This is the output which echoes the blade transformation parameters. The output is displayed for each mesh point, and begins from the line of constant $\eta = 1$ till the last η .

(3) These are the mean relative velocity at the inlet, the Reynolds number at the inlet, and two intermediate parameters.

(4) This is the maximum iteration required, the maximum value of vorticity, the maximum value of the stream function, the maximum value of kinetic energy of turbulence, and the maximum value of dissipation function.

(5) Finally, the values of stream function, meridional velocity, tangential velocity, vorticity, kinetic energy of

turbulence, dissipation energy, Reynolds number and pressure coefficient are displayed for each mesh point. These quantities are presented in groups along constant n lines.

2.3. PROGRAM PROCEDURE

The program is segmented into ten main parts, the subroutines, VORT, STREAM, ENERGY, DSPAT, TEMP, STAPRS, STORE, CONVRG and subroutine function SPLINE are called by the main program. All the subroutines and their relation are shown in figure below. All information which must be transmitted between the ten main subroutines is placed in COMMON.

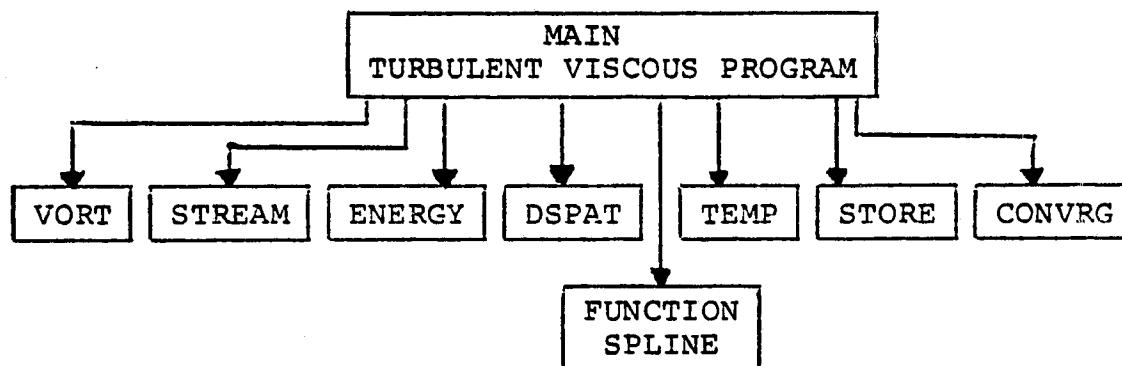


Fig. 2.10. Calling Relation of Subroutines.

TABLE 2.1 BLADE GEOMETRY DATA FOR THE
MIXED FLOW TURBINE

Blade Upper Surface Data

Meridional Distance m(m)	Angular Coordinate ϕ	Angular Derivative	2nd Derivative
0.025340-03	0.56273	-0.45676	-7.2554
0.060000-02	0.55400	-0.46035	6.3594
0.160000-01	0.55560	-0.48120	-11.995
0.235000-01	0.55220	-0.35261	46.288
0.290300-01	0.55050	-0.34501	-43.542
0.342800-01	0.54500	-0.528140-01	154.06
0.395400-01	0.54640	-1.7845	-813.31
0.462300-01	0.51540	-7.6118	-928.77
0.539400-01	0.42000	-15.962	-1242.5
0.616700-01	0.23630	-33.644	-3206.4
0.670110-01	0.238580-01	-50.743	-3497.8

Blade Lower Surface Data

Meridional Distance m(m)	Angular Coordinate ϕ	Angular Derivative	2nd Derivative
0.025340-03	0.547100-02	0.45678	5.7000
0.060000-02	0.122000-01	0.46655	-3.2487
0.160000-01	0.156000-01	0.45729	0.74508
0.235000-01	0.189000-01	0.40262	-15.325
0.290300-01	0.209000-01	0.32213	-13.787
0.342800-01	0.215000-01	-0.26520	-204.96
0.395400-01	0.160000-01	-2.0543	-470.30
0.462300-01	-0.116000-01	-0.6946	-917.03
0.539400-01	-0.962000-01	-15.993	-1495.0
0.616700-01	-0.27910	-30.342	-2078.9
0.670110-01	-0.53070	-50.743	-4303.7

TABLE 2.2. INPUT DATA CARD LISTING.

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OF POOR QUALITY

TABLE 2.2. (Continued)

III. TEAM IDENTIFICATION FOR AMERICAN TEAMS

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OF POOR QUALITY

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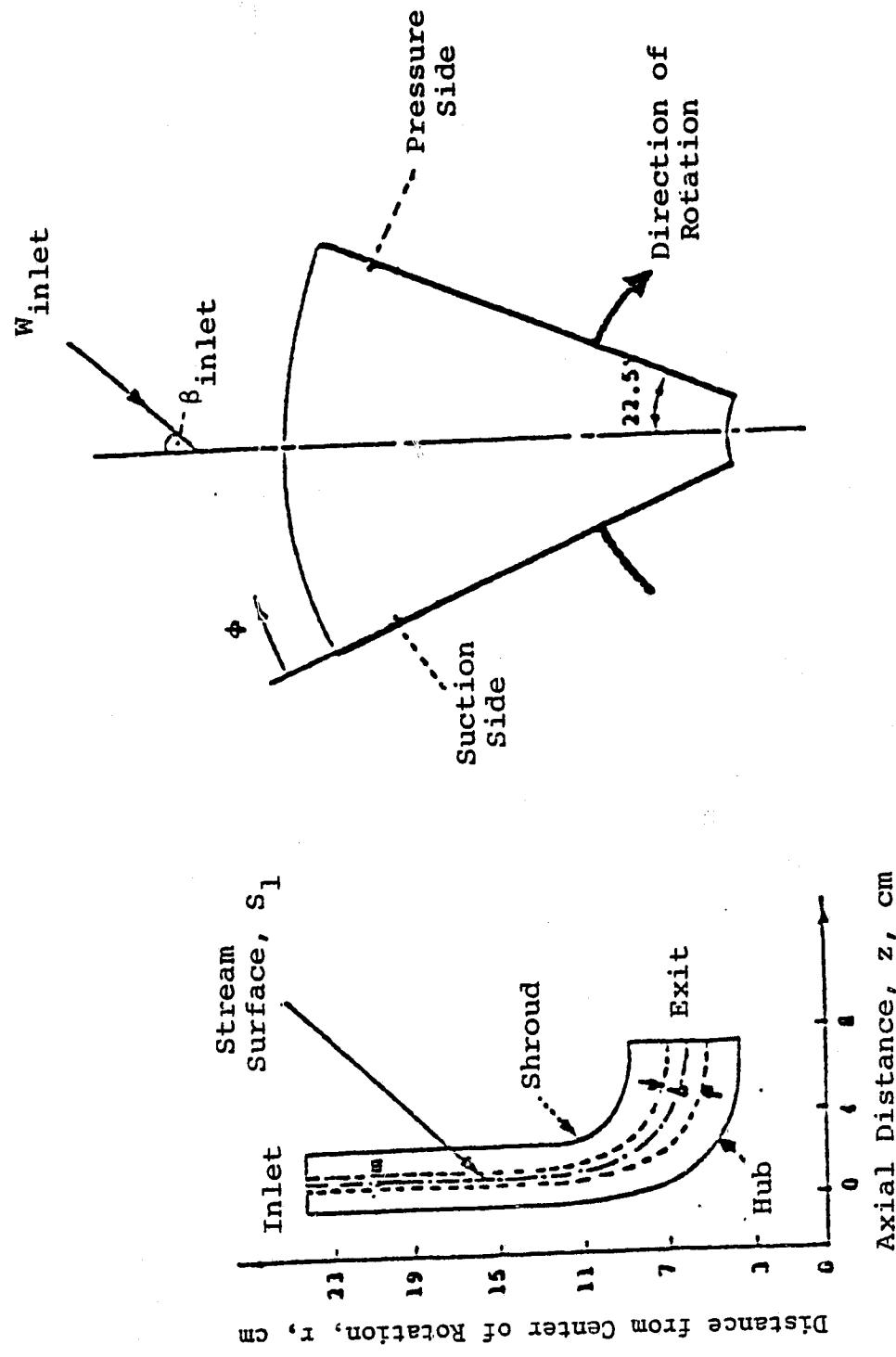
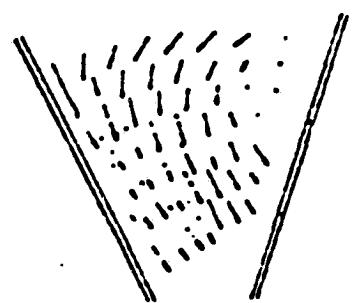
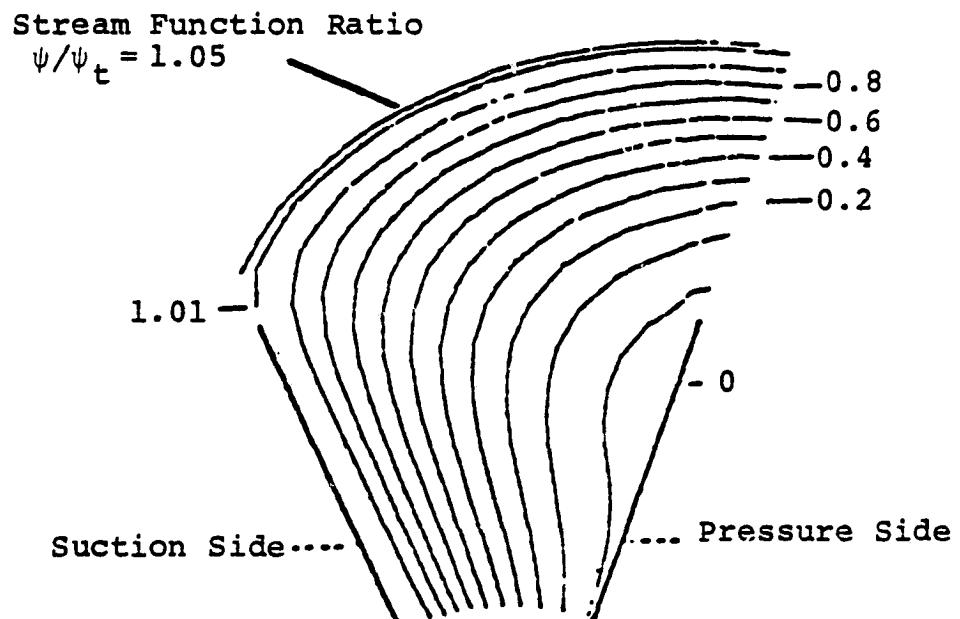


FIG. 1.1. HUB-SHROUD PROFILE WITH THE STREAM SURFACE S_1 ,
USED FOR BLADE-TO-BLADE ANALYSIS.



EXPERIMENTAL CASE

FIG. 1.2. RELATIVE STREAMLINES FOR FLOW THROUGH
 MIXED FLOW TURBINE.

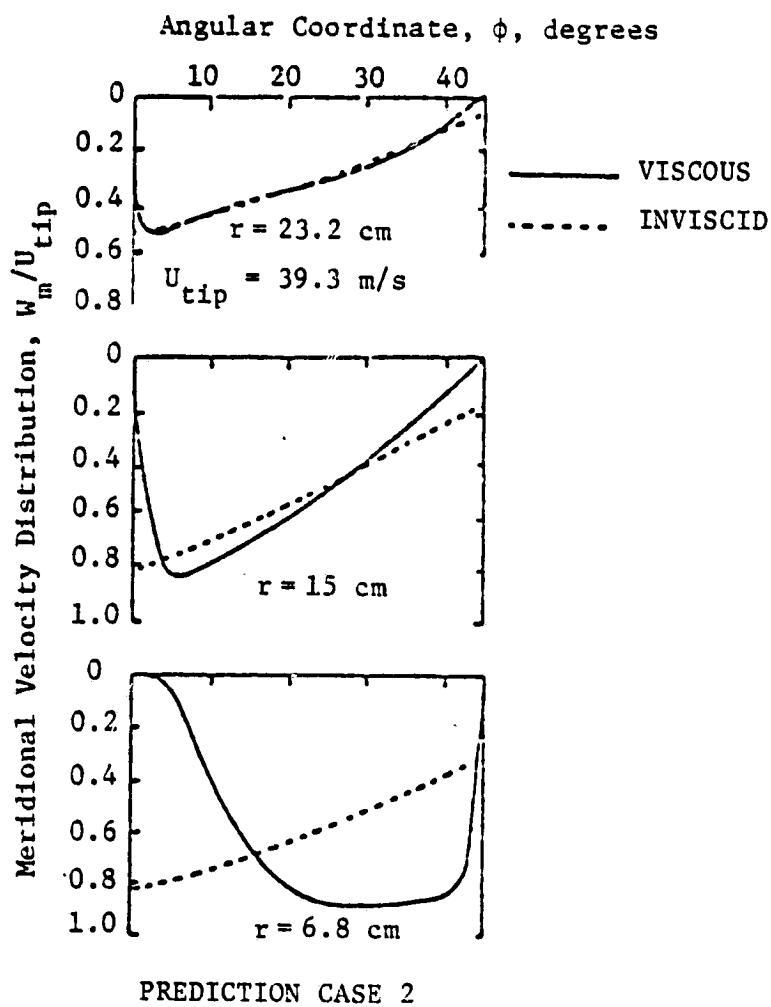


FIG. 1.3. NONDIMENSIONAL VELOCITY DISTRIBUTION AT DIFFERENT RADIAL LOCATIONS.

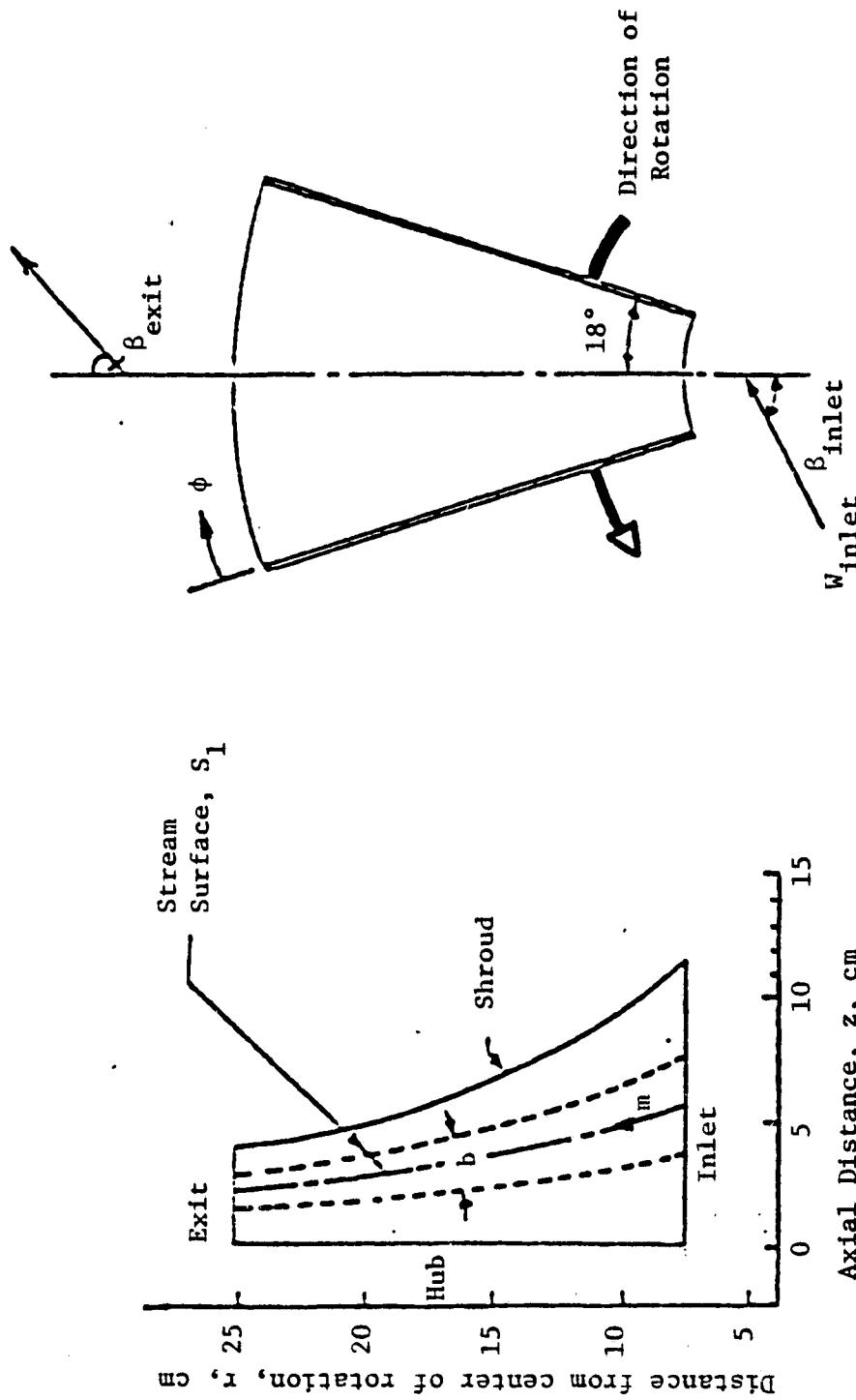


FIG. 1.4. HUB-SHROUD PROFILE WITH THE STREAM SURFACE, S_1 , USED FOR BLADE-TO-BLADE ANALYSIS (COMPRESSOR CASE).

(a) MERIDIONAL VIEW (b) BLADE-TO-BLADE VIEW

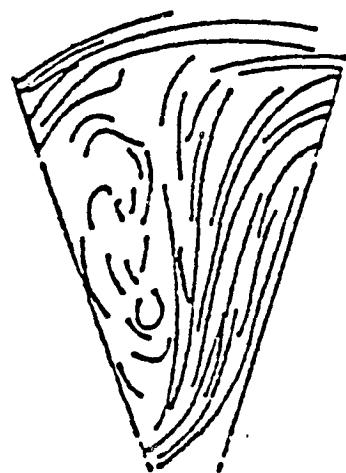
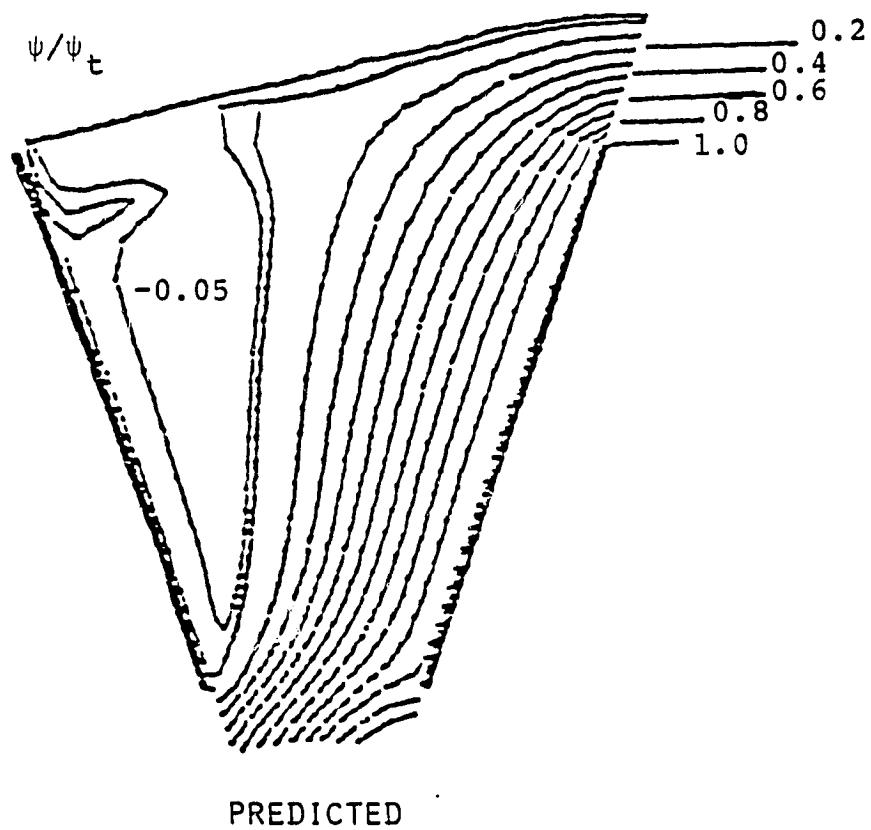


FIG. 1.5. RELATIVE STREAMLINES FOR FLOW THROUGH RADIAL COMPRESSOR.

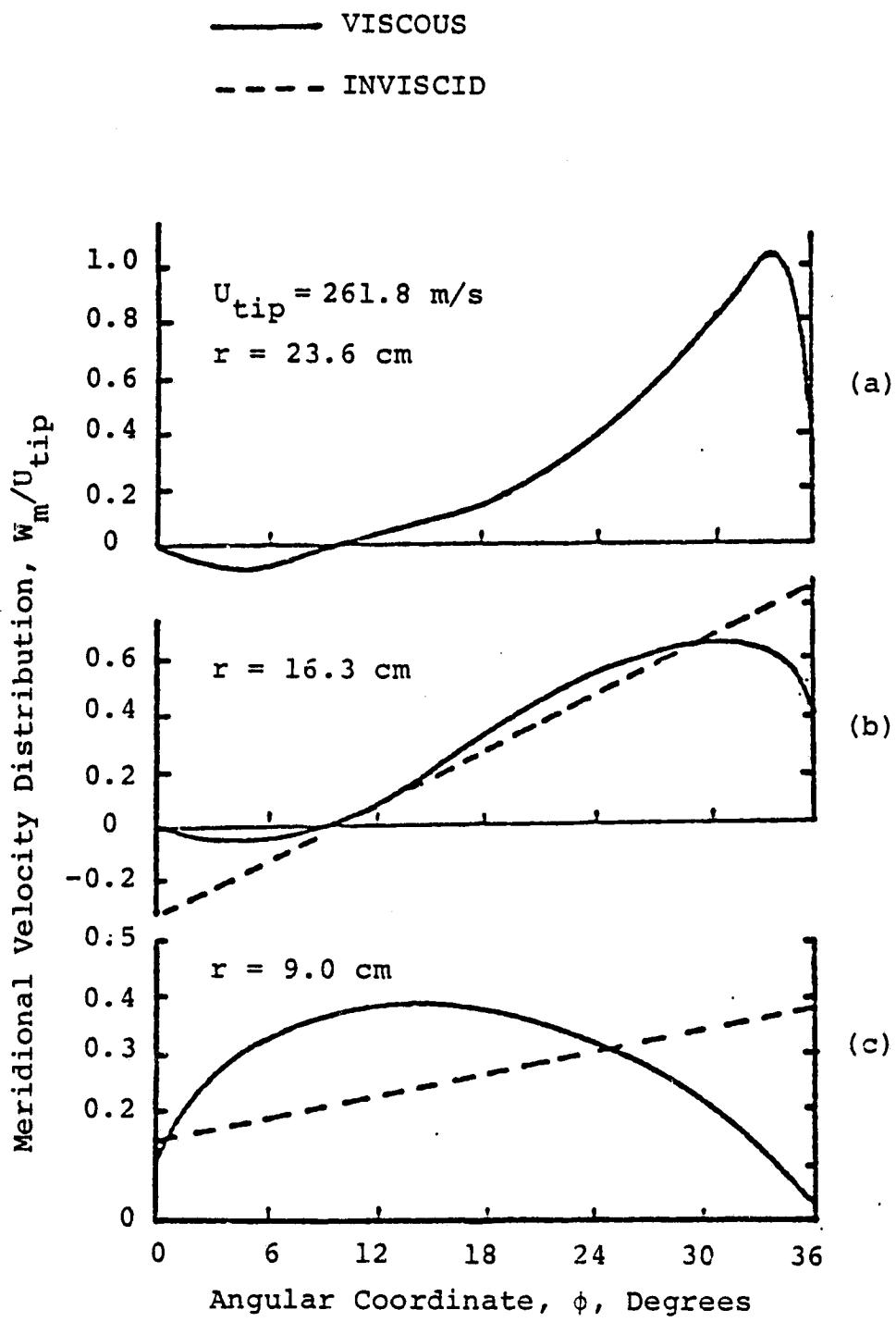
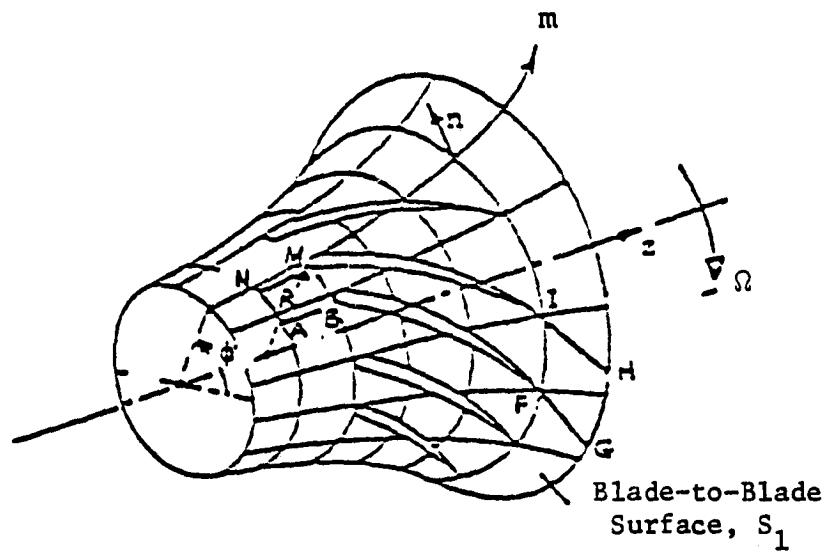
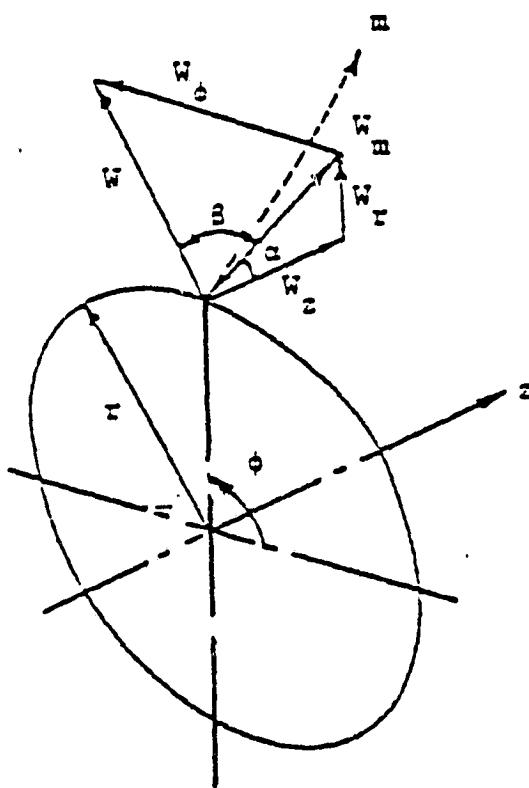


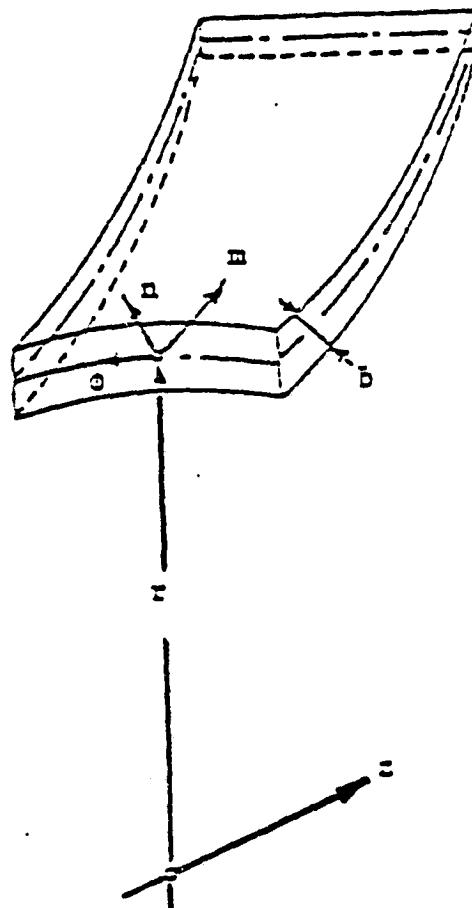
FIG. 1.6. VELOCITY PROFILES ACROSS THE COMPRESSOR PASSAGES AT DIFFERENT RADIAL LOCATIONS



(a) BLADE ROW INTERSECTION WITH A STREAM SURFACE.



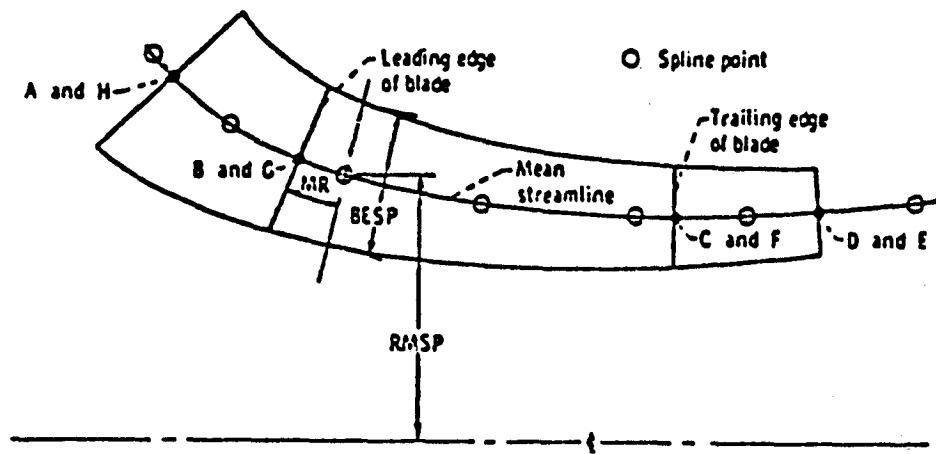
(b) COORDINATE SYSTEM AND VELOCITY COMPONENTS.



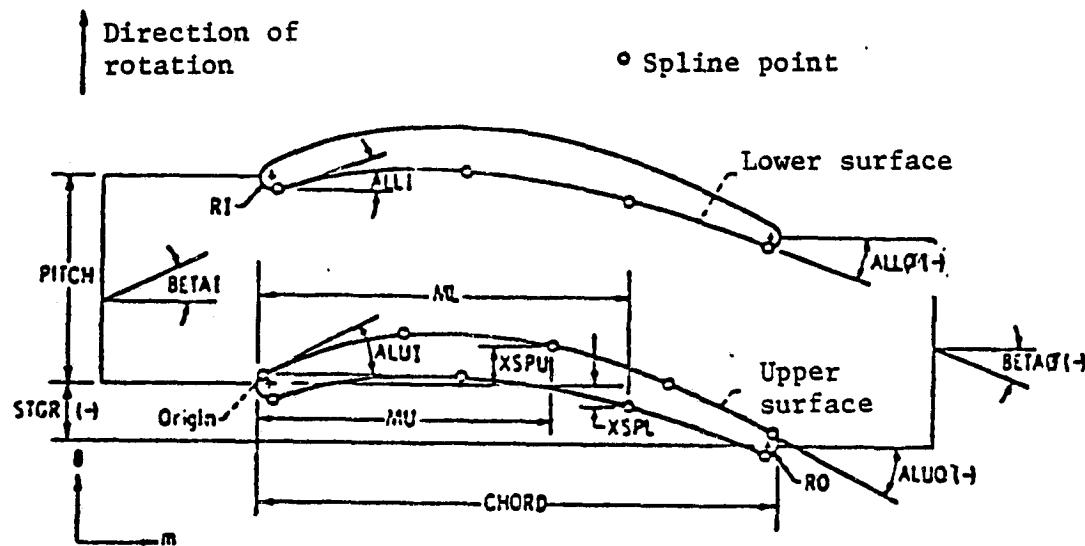
(c) DETAILS OF STREAM SURFACE COORDINATE SYSTEM WITH FINITE THICKNESS SHEET.

FIG. 1.7. BLADE-TO-BLADE STREAM SURFACE S_1 .

FIG. 1.8. INPUT FORM

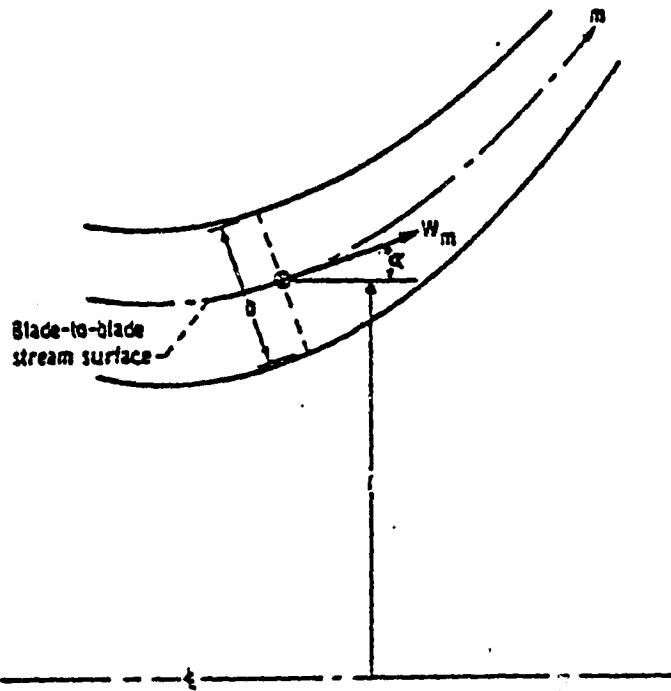


(a) MERIDIONAL PLANE

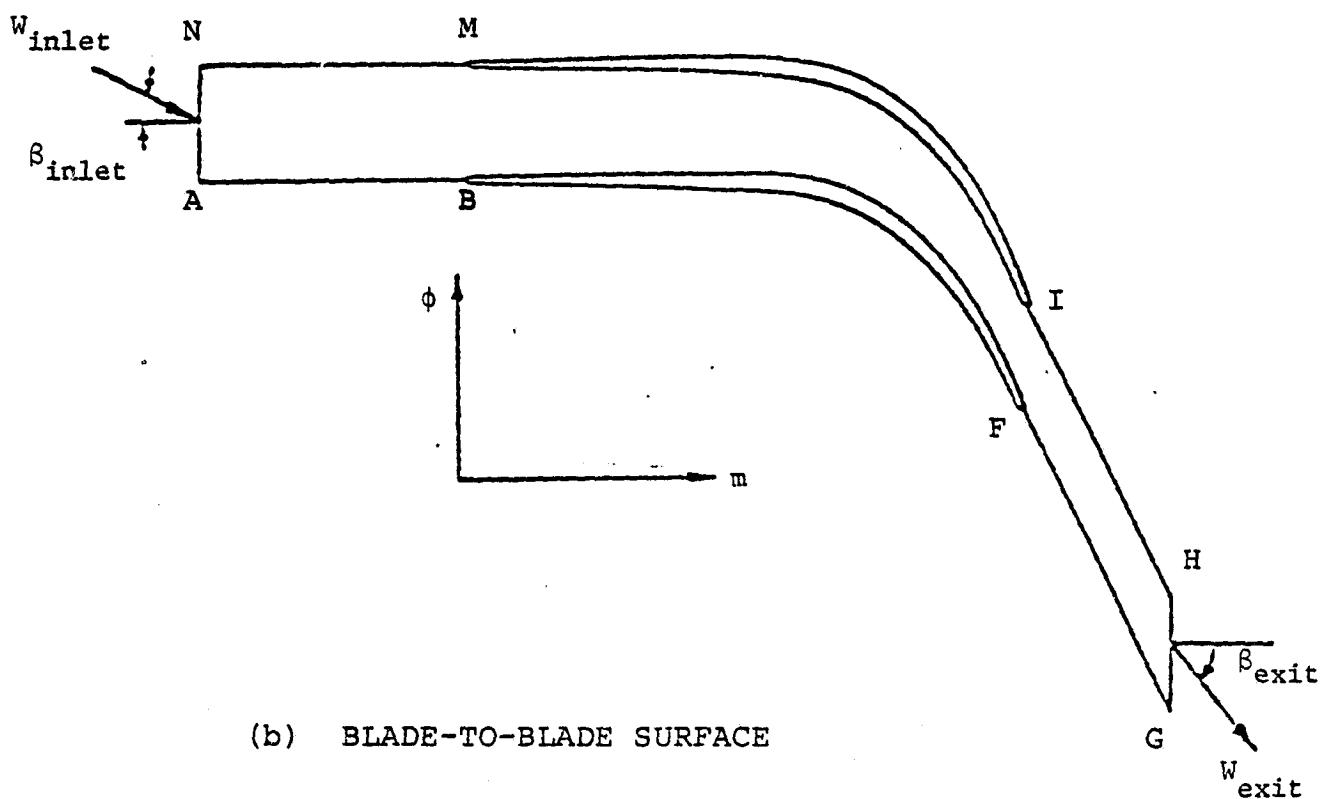


(b) BLADE-TO-BLADE COORDINATES ON STREAM SURFACE.

FIG. 1.9. GEOMETRIC VARIABLES REQUIRED AS INPUT.



(a) MERIDIONAL PLANE



(b) BLADE-TO-BLADE SURFACE

FIG. 1.10. COMPUTATIONAL DOMAIN IN THE PHYSICAL SPACE.

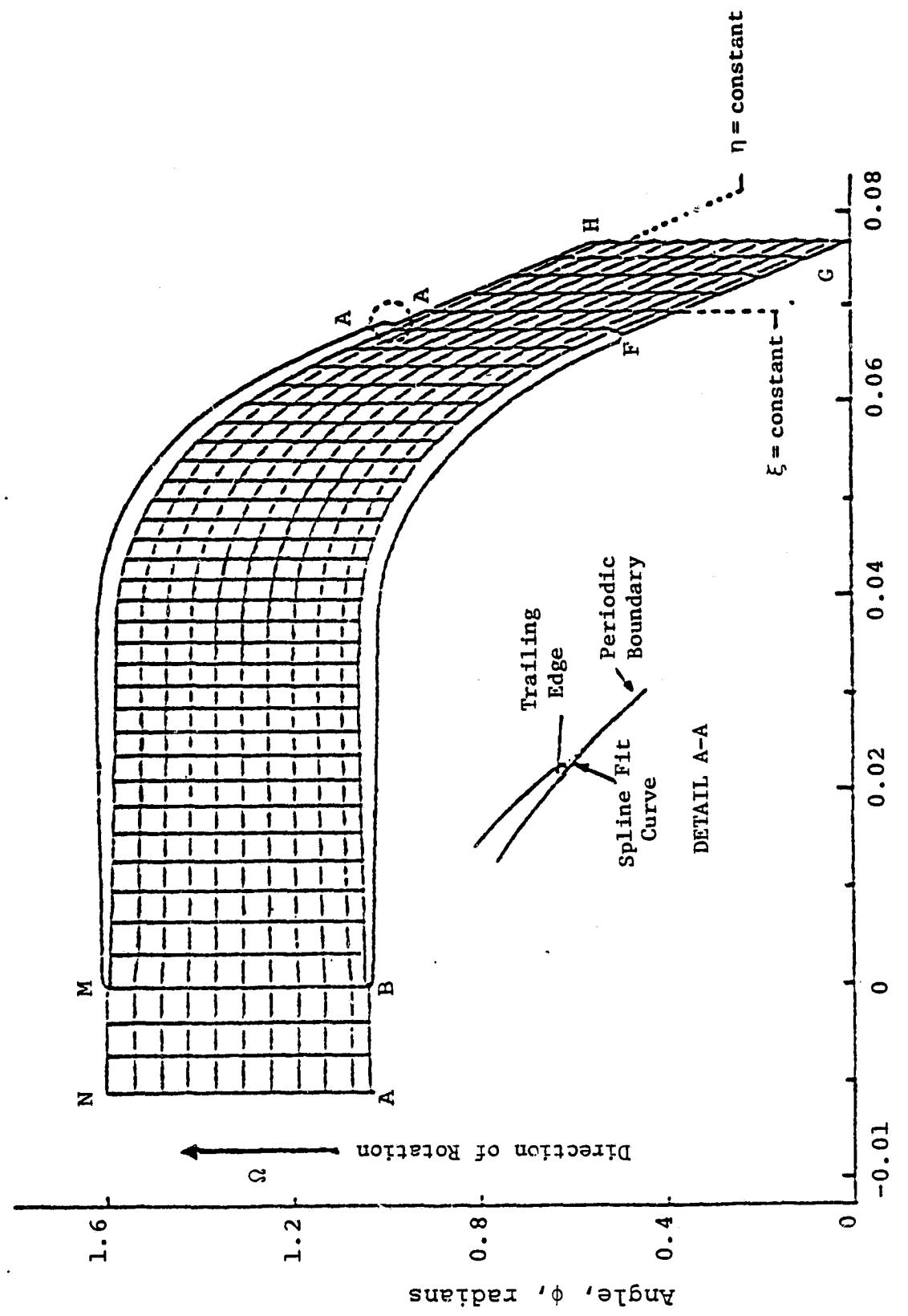
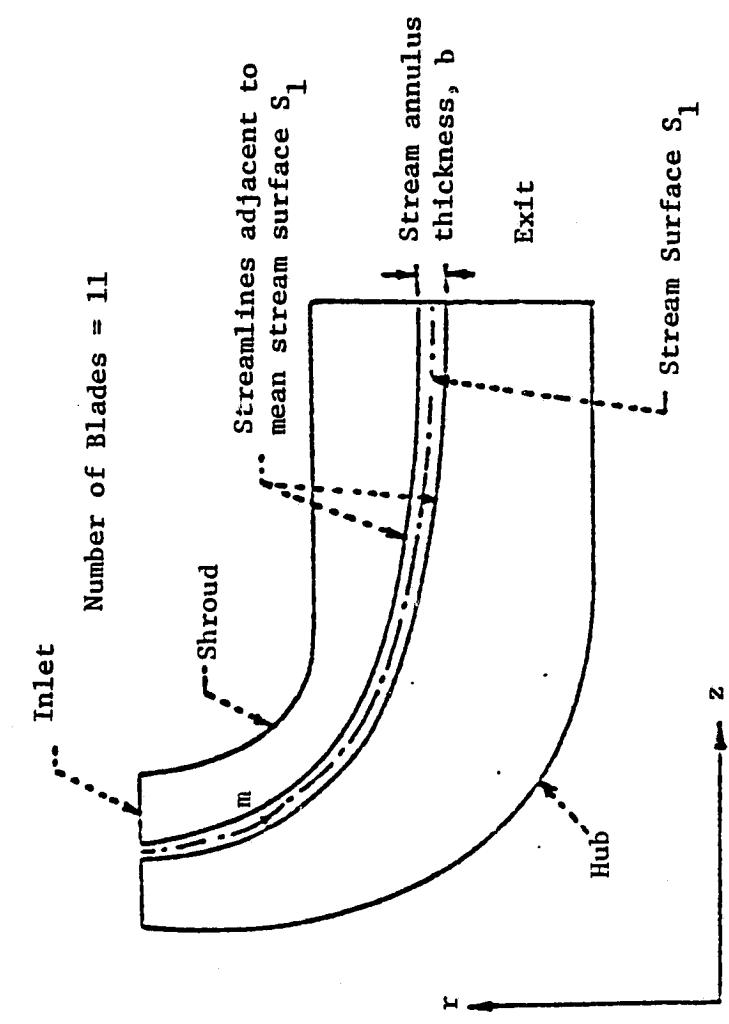
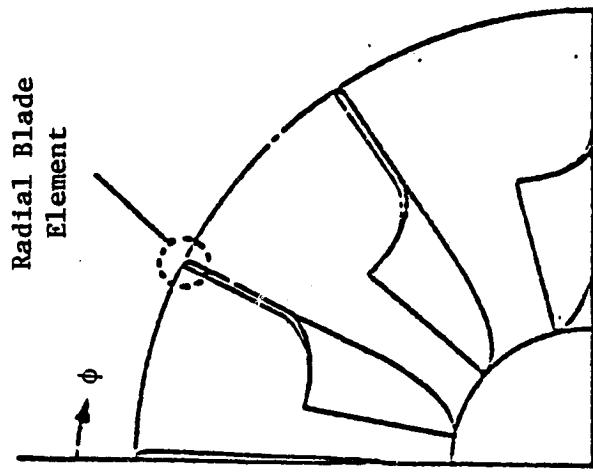


FIG. 1.11. TYPICAL MESH IN BLADE-TO-BLADE SOLUTION REGION.



(a) MERIDIONAL VIEW



(b) BLADE-TO-BLADE VIEW (SCHEMATIC)

FIG. 2.1. HUB-SHROUD PROFILE WITH STREAM SURFACE S_1 , USED FOR BLADE-TO-BLADE ANALYSIS.

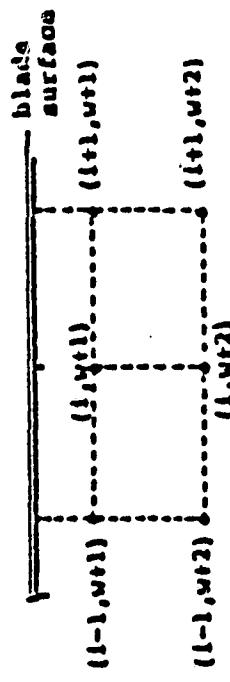
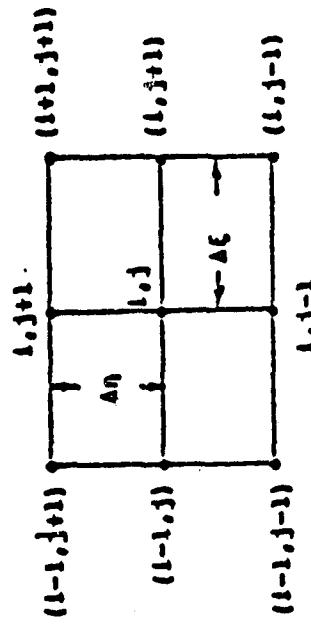
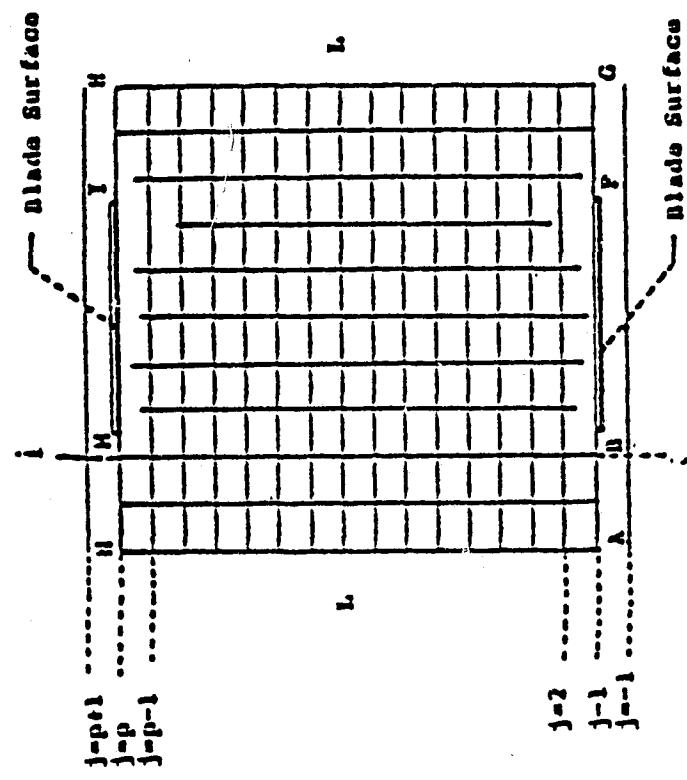


FIG. 2.2. GRID ORDERING SYSTEM IN THE TRANSFORMED DOMAIN

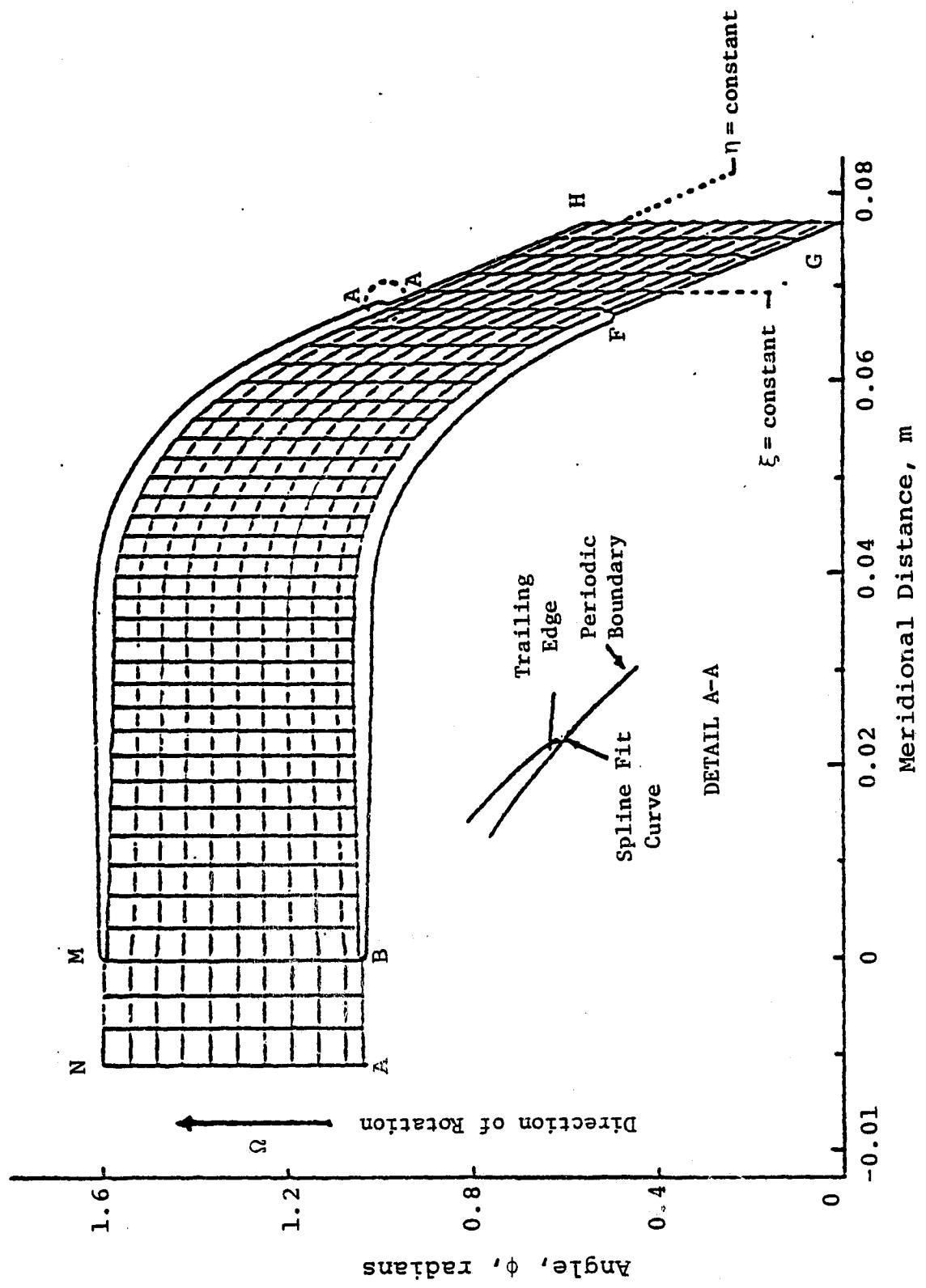


FIG. 2.3. BOUNDARY FITTED COORDINATE SYSTEM FOR THE MIXED FLOW TURBINE ROTOR.

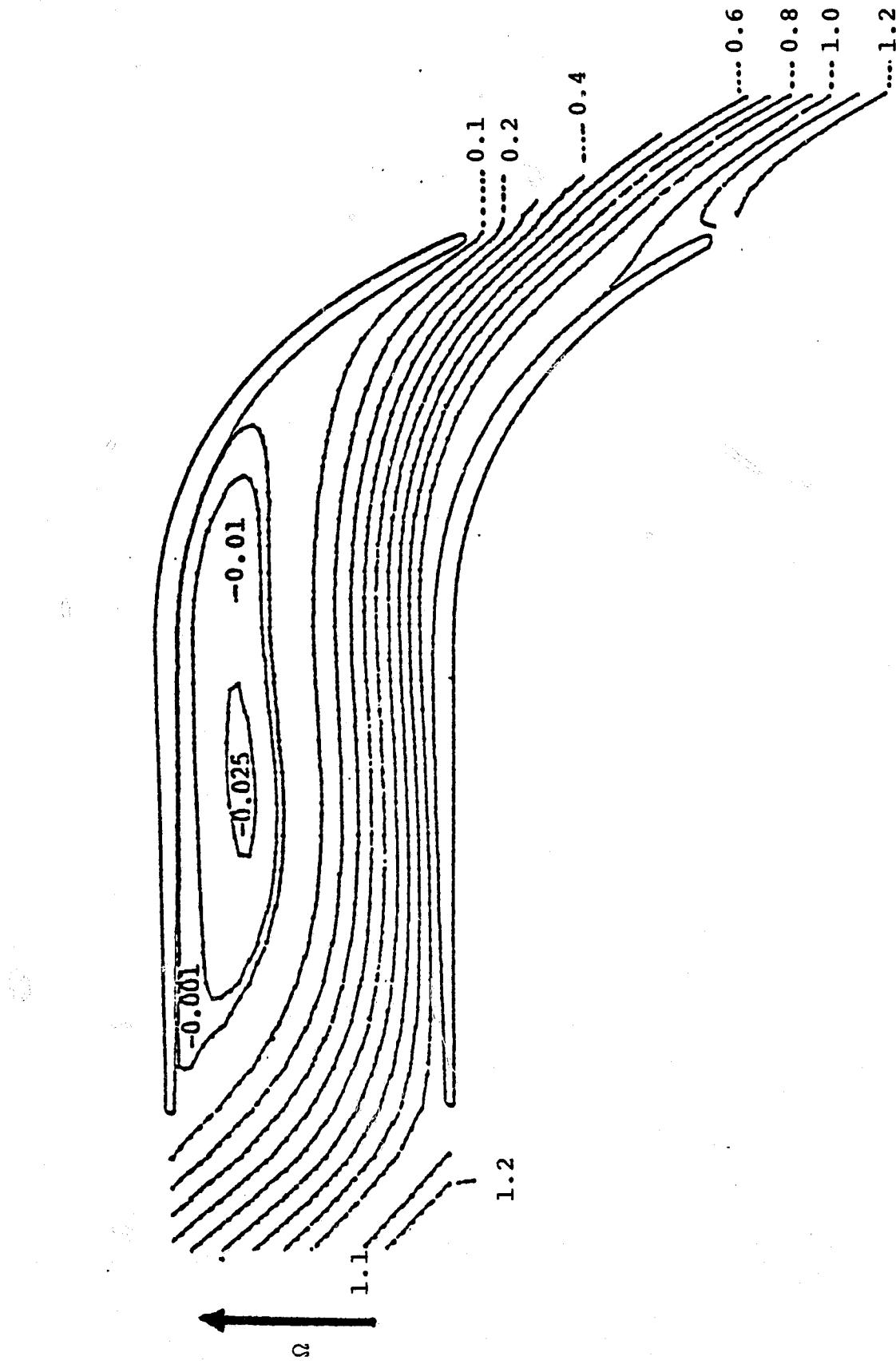


FIG. 2.4. RELATIVE STREAMLINES FOR FLOW THROUGH MIXED FLOW TURBINE.

$$\Omega r_{tip} = 308.1 \text{ m/s}$$

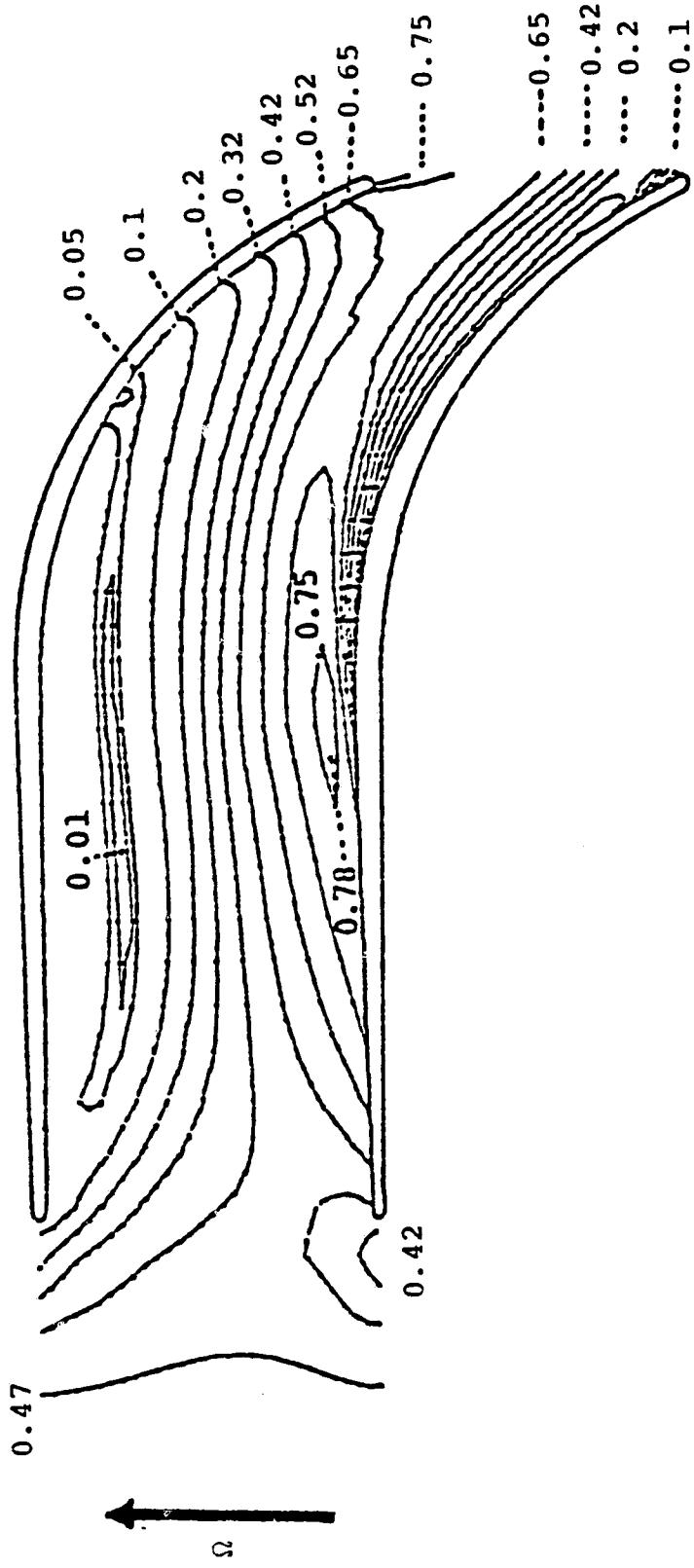


FIG. 2.5. RELATIVE VELOCITY DISTRIBUTION $(w/\Omega r_{tip})$

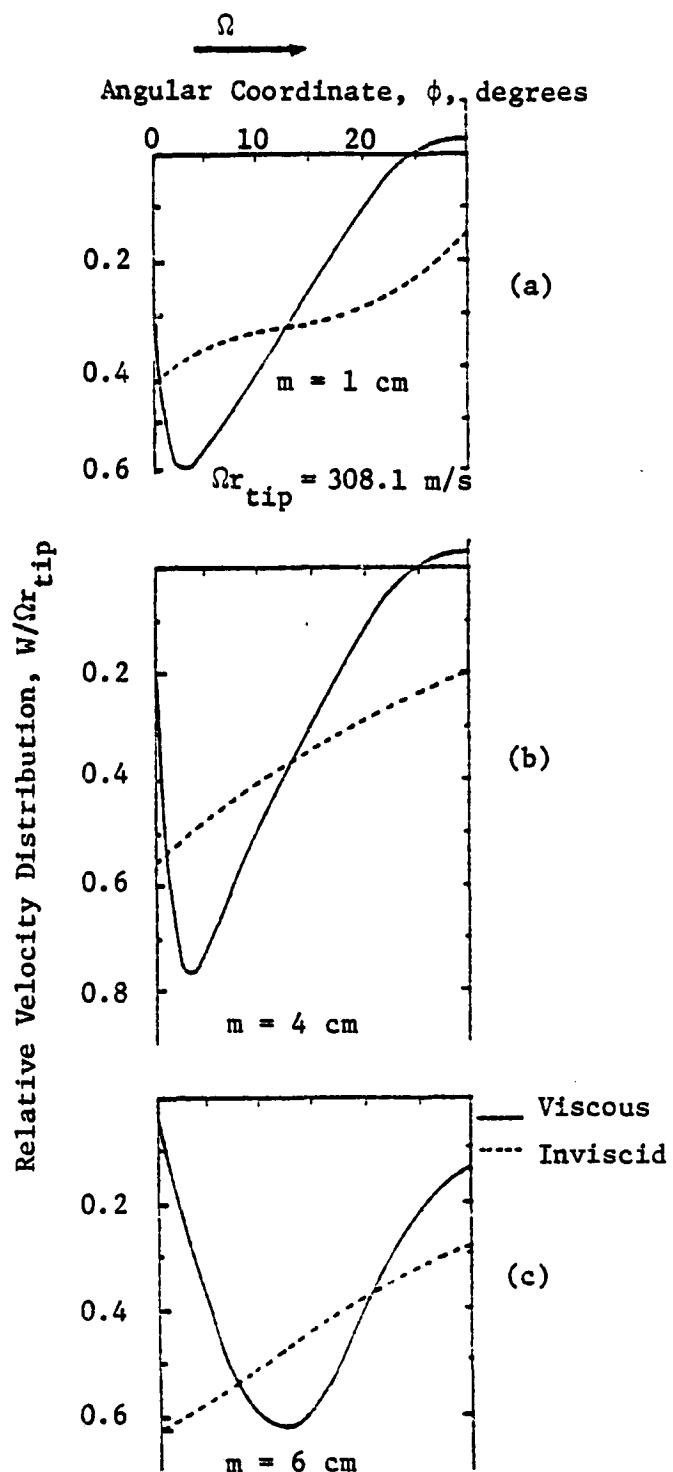


FIG. 2.6. NONDIMENSIONAL VELOCITY DISTRIBUTION AT DIFFERENT MERIDIONAL LOCATIONS.

$$\Omega r_{tip} = 308.1 \text{ m/s}$$

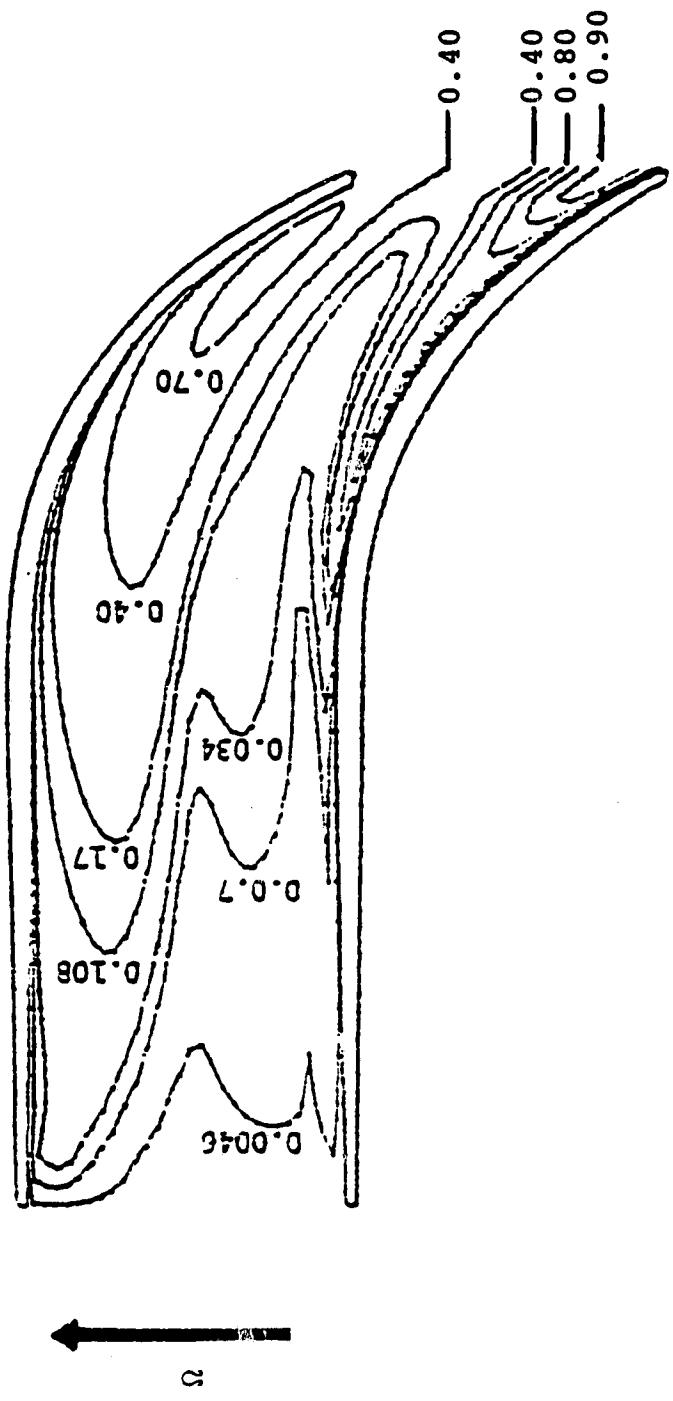


FIG. 2.7. KINETIC ENERGY OF TURBULENCE DISTRIBUTION [$(E/\Omega^2 r_{tip}^2) \times 10^2$]

$$\Omega r_{tip} = 308.1 \text{ m/s}$$

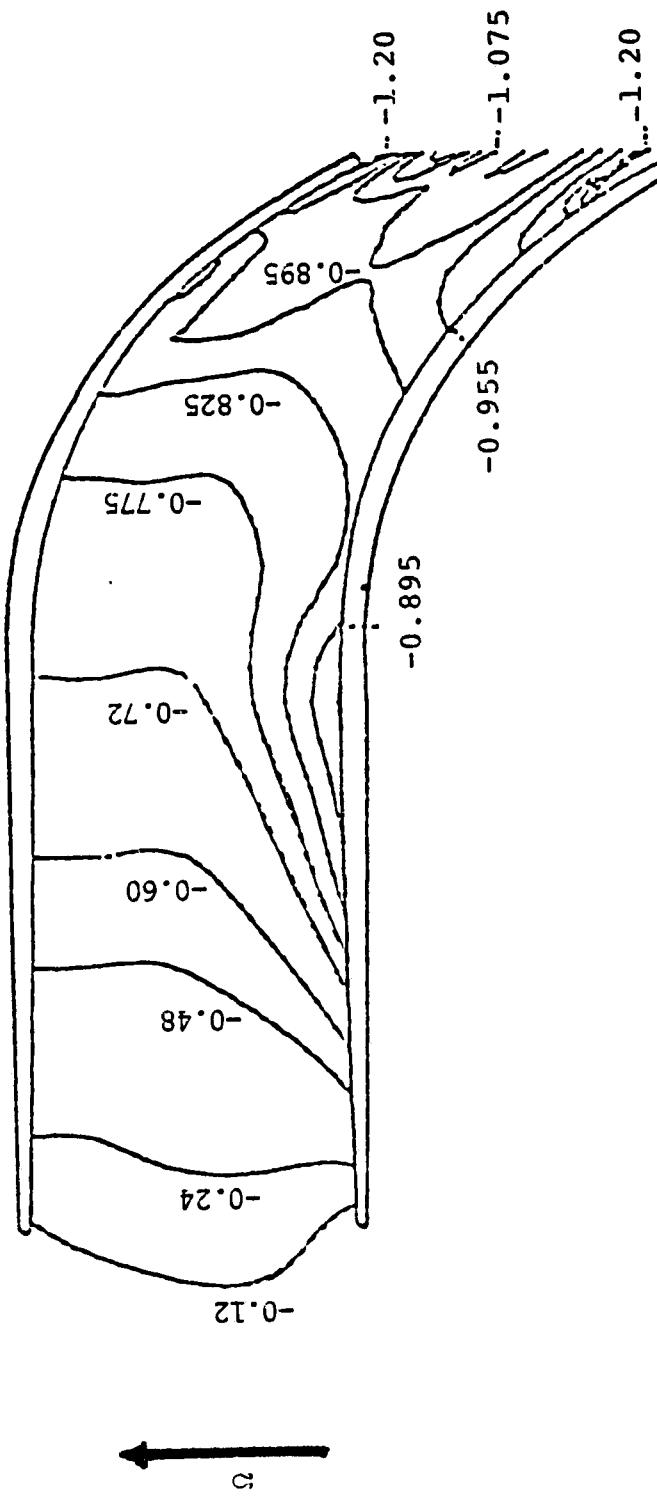


FIG. 2.8. STATIC PRESSURE DISTRIBUTION $[(p - p_{inlet}) / \frac{\rho}{2g} \Omega^2 r_{tip}^2]$

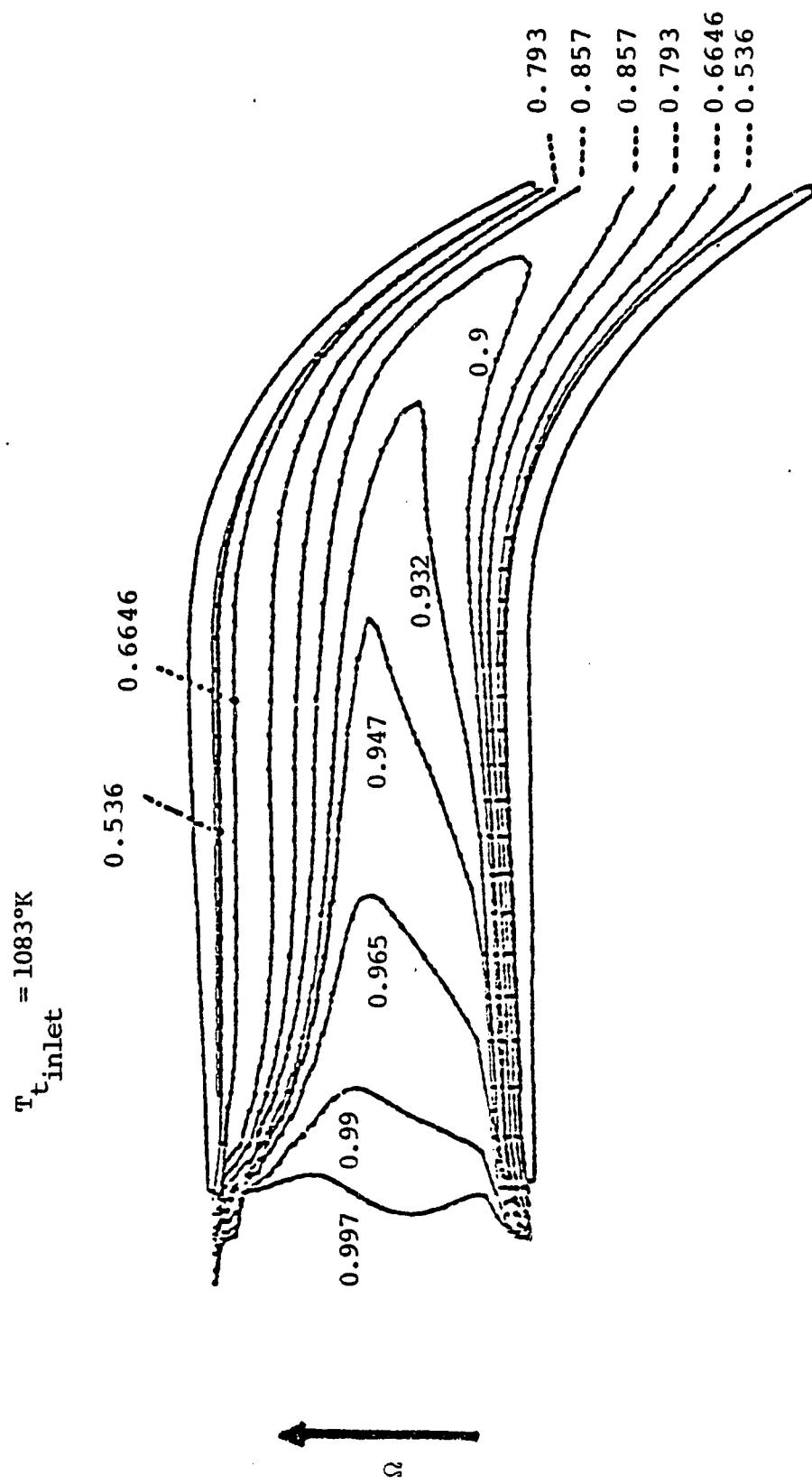


FIG. 2.9. STATIC TEMPERATURE DISTRIBUTION [$T/T_{t_{\text{inlet}}}$]